



City Council Staff Report

Subject: Landscape Maintenance Agreement

Date: February 25, 2025

Submitted By: Rick Lawrence, Public Works Manager
Justin Nartker, Public Works Director

Department: Public Works

Recommendation:

Adopt a Resolution of the City Council of the City of Rocklin Approving a Landscape Maintenance Agreement and Authorizing the City Manager to Execute the Landscape Maintenance Agreement with Chapa-De Indian Health Program, Inc.

Background:

On August 6, 2024, the Rocklin Planning Commission adopted Resolution No. PC-2024-25 (Attachment 2), approving the Design Review of the Chapa-De Indian Health South Placer Facility. As part of the approval, the Developer (Chapa-De) has agreed to maintain the City-owned landscape area within the City-owned right-of-way along the Chapa-De perimeter, located on Wildcat Boulevard and West Stanford Ranch Road. Chapa-De will maintain the landscape and irrigation system on the City-owned right-of-way located on Wildcat Boulevard and West Stanford Ranch Road, as identified on the Project Location Map (Attachment 3).

A Landscape Maintenance Agreement is required to formalize this arrangement. This agreement will ensure a uniform landscape treatment and simplify maintenance responsibilities. This agreement provides a benefit to both Chapa-De and the City by eliminating the need to install duplicative irrigation systems for both the project frontage and the City's right-of-way. It also provides the Developer control of the aesthetics of their frontage and long-term maintenance savings to the City. The agreement requires the Developer to maintain proper insurance coverage, naming the City as an additional insured. The agreement also includes the City's standard hold harmless provision.

Staff has determined that this agreement is beneficial to both Chapa-De and the City and recommends approval.

Fiscal Impact:

There is no direct fiscal impact to the General Fund from the staff recommendation.

ATTACHMENTS:

1. Resolution and Agreement
2. Planning Commission Resolution PC-2024-25
3. Project Location Map